

CONTENTS

1	PREFACE	<i>xiii</i>	
0	INTRODUCTION—MODELING	1	
	<i>References</i>	5	
1	MODELS OF NEURONS	6	
	1-1 Basic Biophysics Tools		6
	1-1-1 Diffusion of uncharged particles in aqueous solutions	7	
	1-1-2 Drift of charged particles in aqueous solutions		10
	1-1-3 The Einstein relationship	13	
	1-2 Equilibrium in a One-Ion System		14
	1-3 Donnan Equilibrium		17
	1-4 Space-Charge Neutrality		18
	1-5 Voltage Across a Membrane with Nonzero Permeability for All Ions		21

1-6	The Goldman Equation	23
1-7	Ion Pumps	26
1-8	Membrane Potentials for Biological Membranes	27
1-9	The Hodgkin-Huxley Model	31
1-10	The Iron-Wire Model	38
1-11	Summary	39
	References	40
	Problems	42
2	BIOINSTRUMENTATION	45
2-1	Electrodes	46
	2-1-1 <i>The electrode-electrolyte model</i>	46
	2-1-2 <i>The half-cell potential</i>	47
	2-1-3 <i>Silver-silver chloride electrodes</i>	49
	2-1-4 <i>Electrode models</i>	50
	2-1-5 <i>Microelectrodes</i>	53
2-2	Amplifiers	55
	2-2-1 <i>Differential amplifiers</i>	55
	2-2-2 <i>Operational amplifiers</i>	57
2-3	Digital Techniques	66
2-4	Patient Lead Devices	67
	2-4-1 <i>Diode circuits</i>	68
	2-4-2 <i>JFET limiters</i>	70
	2-4-3 <i>Isolated leads</i>	72
2-5	Summary	73
	References	75
	Problems	76
3	OPEN-LOOP SYSTEMS	79
3-1	Why Use Laplace Transforms?	79
3-2	The Impulse Response	83

3-3	The Identification Problem	84
3-4	Laplace Transform of a Time Delay	89
3-5	Transfer Function of a Crayfish Photoreceptor Ganglion	91
3-6	Mathematical Analysis of Linear Second-Order Systems	96
3-6-1	<i>The transfer function</i>	96
3-6-2	<i>Poles and zeros</i>	98
3-6-3	<i>Pole-zero plots on the complex plane</i>	102
3-6-4	<i>Step response of a second-order system</i>	103
3-6-5	<i>Frequency response of a second-order system</i>	107
3-7	Models for Human Movement	112
3-7-1	<i>The eye-movement control system</i>	112
3-7-2	<i>Four eye-movement systems</i>	113
3-7-3	<i>Quantitative eye-movement models</i>	115
3-7-4	<i>Techniques for validating models</i>	153
3-7-5	<i>Validation of other physiological models</i>	175
3-7-6	<i>Parameter estimation</i>	176
3-7-7	<i>Linearizing the model</i>	177
3-8	Summary	187
	References	188
	Problems	195
4	CLOSED-LOOP SYSTEMS	201
4-1	Why Use Closed-Loop Systems?	203
4-1-1	<i>Reduction of sensitivity to plant-parameter variations</i>	203
4-1-2	<i>Reduction of sensitivity to output disturbances</i>	206
4-2	Speed of Response	209
4-3	Stability	211
4-3-1	<i>Root-locus plots</i>	212
4-3-2	<i>Opening the loop</i>	214
4-3-3	<i>Bode diagrams</i>	215
4-3-4	<i>Nyquist plots</i>	217
4-3-5	<i>Instability in nonlinear systems</i>	221

4-4	The Neuromuscular System	221
4-4-1	<i>The stretch reflex</i>	221
4-4-2	<i>The antagonist muscle</i>	224
4-4-3	<i>Two control mechanisms</i>	225
4-4-4	<i>Golgi tendon organs</i>	228
4-4-5	<i>Experimental validation of the model</i>	231
4-4-6	<i>Parkinson's syndrome</i>	233
4-5	Thermoregulation Systems	234
4-5-1	<i>Model of the plant</i>	237
4-5-2	<i>Controller model</i>	238
4-5-3	<i>Model validation</i>	240
4-5-4	<i>Model variations</i>	242
4-5-5	<i>Industrial applications</i>	244
4-6	Summary	244
	References	245
	Problems	247
5	ELECTRICAL SAFETY	255
5-1	Types of Hazards	255
5-1-1	<i>Physiological harm</i>	255
5-1-2	<i>Static electricity</i>	257
5-1-3	<i>Explosion hazard</i>	258
5-1-4	<i>Interruption of power</i>	258
5-2	Ways of Ameliorating the Situation	258
5-2-1	<i>The three-wire electrical distribution system</i>	258
5-2-2	<i>Ground integrity</i>	260
5-2-3	<i>Single-point grounding</i>	261
5-2-4	<i>Grounding in critical care area</i>	264
5-2-5	<i>Isolation transformers</i>	268
5-2-6	<i>Double insulation</i>	269
5-2-7	<i>Good engineering design</i>	270
5-3	Leakage Current	271
5-3-1	<i>Dangers of leakage currents</i>	272
5-3-2	<i>Leakage current testing</i>	274

5-4	Plugs and Receptacles	278
5-4-1	Receptacle wiring	278
5-4-2	Receptacle force testing	281
5-4-3	Pin configurations	281
5-4-4	Grades of plugs and receptacles	283
5-5	Ground Fault Monitors	284
5-5-1	Current monitors	285
5-5-2	Voltage monitors	286
5-5-3	Ground-fault interruptors	288
5-6	Human Subjects	288
5-7	Medical Device Amendments of 1976	290
	References	291
	Problems	293
6	LABORATORIES	295
6-1	Electrocardiology	295
6-2	Circuit Design Constraints	296
6-3	Electromyogram (EMG)	296
6-4	Electroencephalogram (EEG)	296
6-5	Electro-oculogram (EOG) and Photoelectric Measurements	297
6-6	Clinical Engineering	297
6-7	Radiology	297
6-8	Blood Flows	298
6-9	Pressure	298
6-10	Digital Computer Techniques	298
6-11	Electrode Impedance	298
	References	299
INDEX	301	