CONTENTS Nº 2705

Chapter 1		C DEFINITIONS, DETERMINANTS, AND LINEAR ALGEBRA ATIONS 1	JC
	1.1.	Introduction	1
	1.2	Determinants of the Second Order	1
	1.3	Properties of Determinants	2
	1.4	Multiplication of Determinants	2
	1.5	Two Simultaneous Linear Algebraic Equations in Two	
		Unknowns	3
	1.6	Unknowns	4
	1.7	Expansion of Determinants of the <i>n</i> th Order	5
	1.8	Fundamental Properties of Determinants	6
	1.9	Method of Chiò for Evaluating Determinants	8
	1.10	The Solution of Linear Equations by Determinants,	
		Cramer's Rule	12
	1.11	n Homogeneous Equations in n Unknowns	14
	1.12	Gauss' Method of Elimination in Solving Simultaneous	
		Equations	15
	1.13	Triangulation Method in the Solution of Simultaneous	
		Equations	16
Chapter 2	MAT	TRIX ALGEBRA, SIMULTANEOUS EQUATIONS 22	
	2.1	Introduction	22
	2.2	Definitions and Notation	22
	2.3	Elementary Operations on Matrices	23
	2.4	Multiplication of Matrices	24
	2.5	Partitioned Matrices and Partitioned Multiplication .	26
	2.6	Matrix Division; the Inverse Matrix	28
	2.7	Solution of Simultaneous Equations by Matrix Inversion	31
	2.8	Augmented Matrix Method of Matrix Inversion	32
	2.9	Gauss-Seidel Method of Solving Simultaneous Equations	38
		Representation of Vectors by Matrices	41
		Coordinate Transformation Using Matrices	43

2.12 The Vector Product of Two Vectors	44
2.13 Linear Dependence of Vectors .	46
2.14 Linear Independence of Vectors and the Gram Deter-	40
minant .	
	48
Chapter 3 EIGENVALUES, EIGENVECTORS, AND QUADRATIC FORMS	55
3.1 Introduction .	55
3.2 The Eigenvector (Characteristic Vector) Equation	55
3.3 Fundamental Properties of the Characteristic Polynomial	33
of Matrix A	59
3.4 Properties of the Eigenvectors of a Square Matrix	62
3.5 The Case of Repeated Eigenvalues	66
3.6 Matrix Iteration Method of Evaluating Eigenvalues and	00
Eigenvectors	69
3./ Iteration Method for Obtaining the Smallest Character	0)
istic Values and Vectors.	76
ose of Orthogonality Relations in Obtaining Character-	70
istic values and Vectors	77
3.9 The Method of A. M. Danilevsky for Obtaining the	11
Characteristic Equation	81
3.10 Characteristic Vector by the Method of A. M. Danilevsky	88
3.11 The Relation Between the Eigenvectors and Eigen-	00
Values of a Matrix and These -CL T	00
3.12 The Gram-Schmidt Orthogonalization December 1	89
3.13 The Modal Matrix and the Quadratic Forms	90
	91
Chapter 4 FUNCTIONS OF MATRICES; MATRIX CALCULUS AND MATRICES	ΓRΙΧ
DIFFERENTIAL EQUATIONS 99	I ICIZE
4.1 Introduction .	99
4.2 Polynomials in a Square Matrix, with Scalar Coefficients	99
4.3 Power Series of Matrices	100
4.4 Matrix Functions	101
4.5 Some Properties of the Matrix Exponential Function	101
4.0 Rational Functions of Matrices	103
4.7 Eigenvalues of Rational Functions of Matrices (Fro-	
benius's Theorem)	103
4.8 The Cayley-Hamilton Theorem	104
4.9 The Reduction of Matrix Polynomials4.10 Reduction of Functions of Matrices	106
4.10 Reduction of Functions of Matrices .	107
4.11 Reduction of Functions of nth order Matrices	110
4.12 Reduction of Polynomials and Functions of Matrices	
with Multiple Eigenvalue	112
NAMES - SANON - AND - AND - SANON - AND - SANON - AND - SANON - AND - SANON - AND - SA	

Contents	ix

	4.13	Differentiation and Integration of Matrices	112
		Simultaneous Linear Differential Equations of the First	
	*	Order with Constant Coefficients	114
	4.15	Solution of a Homogeneous Set of Linear Differential	
		Equations of the Second Order	116
	4.16	Simultaneous Linear Differential Equations of the First	
		Order with Variable Coefficients	117
	4.17	The Determination of the Transition Matrix by the	
		Method of Picard	119
	4.18	Computation of the Transition Matrix $P(t)$	122
		Certain Numerical Methods for the Determination of	
		the Transition Matrix $P(t)$	123
	4.20	The Method of Mean Coefficients for Evaluating $P(t)$.	127
	4.21	A Perturbation Method for the Determination of the	
		Transition Matrix $P(t)$	129
	4.22	A Method for the Computation of the Transition	
		Matrix $P(t)$ for a Constant Matrix A .	131
		CORDIGAL ADDITIONS OF MATRICES AND	
Chapter 3		CTRICAL APPLICATIONS OF MATRICES 141	
	5.1	Introduction	141
	5.2	Fundamental Principles	141
	5.3	The General Circuit on a Loop Basis	143
	5.4	The Laplace Transform	146
	5.5	The General Solution of the Loop Equations	150
	5.6	The Single-Loop Case	152
	5.7	The Steady-State Solution of the <i>n</i> -Loop Circuit; Alter-	
		nating Currents	155
	5.8	The Nodal Equation of the General Network	156
	5.9	Four-Terminal Networks in the Alternating Current	
		Steady State	160
		Reversed Four-Terminal Networks	162
	5.11	The Series Interconnection of Four-Terminal Net-	PT 1000001
		works	163
	5.12	Wave Propagation Along a Series of Four-Terminal	
		Networks	166
	5.13	Networks Wave Propagation Along a Series of Reversible	
		Structures	170
	5.14	Elementary Filter Circuits	172
	5.15	Steady-State Analysis of Two-Conductor Transmission	\$50 MARKET #184
		Lines	176

X	Contents
Λ	

Chapter 6		E-FREQUENCY DOMAIN ANALYSES AND THE FAS NSFORM 182	ST F	OUF	RIER
	6.1	Introduction			182
		Discrete Fourier Transform			183
	6.3		•		187
	6.4	Numerical Examples			190
	6.5	Computer Program for the Calculation of the F	our	ier	
		Transform			194
	6.6	Cooley Takey Method			
	6.7	Discussion of Fourier Transforms			201
	6.8	Licelife Circuit / illuly 515 ill tille 1 illie		•	202
	6.9	The Free Oscillations of the Circuit			
	6.10	Solution in Terms of Functions of Matrices			
	6.11	The General Case, Forced Oscillations .			208
		MULATION OF VIBRATION PROBLEMS (CO	NSE	RVA'	TIVE
	SYS	TEMS) 213			212
	7.1		•	•	
	7.2		C E		213
	7.3		1 F	ee-	217
		dom		•1	217
	7.4	The Free Oscillations of a Linear Conservative	Syst	em	225
		with n Degrees of Freedom			225
	7.5	Normal Coordinates in the Case of n Degrees o			220
		dom	•		229
	7.6	Examples of the General Theory	•	•	230
	7.7				233
-	7.8		٠		235
	7.9	Use of Matrix Iteration in Determining the Frequency	uen	cies	
		and Modes of Oscillation of Linear Conse			0.20
		Systems			238
	7.10	Numerical Example of the Iteration Procedure			241
*	7.11	Determination of the Higher Modes; the Sw	veep	ing	
		Matrix	•	•	244
	7.12	Matrix	•	•	247
Chapter 8		MULATION OF VIBRATION PROBLEMS (NONCO TEMS) 258	NSE	RVA	
	8.1	Introduction			
		The Reduced Equations			259
		Separated Coordinates			262

ontents			XI
	8.4	The Forced Oscillations	262
		The Analysis of a Class of Symmetric Damped Linear	
		Systems	263
	8.6	Matrix Iteration Method for Damped Vibrations.	265
	8.7	Determination of the Frequencies and Modes	267
	8.8	Completion of the Solution	271
	8.9	Transformation of the Equations of Motion and Normal	
		Coordinates	273
	8.10	Remarks on Numerical Procedures	274
	8.11	Numerical Example	274
	8.12	The Routh-Hurwitz Stability Criterion	280
		CONTROL AND ACCUMENT OF MARRIAGES 204	
hapter 9	STRU	UCTURAL APPLICATION OF MATRICES 284	
	9.1	Introduction	284
	9.2	Stiffness and Flexibility Matrices	284
	9.3	Equations of Motion	292
	9.4	Internal Forces, Deformation, and Internal Energy .	
	9.5	Matrix Force Method of Calculating Stiffness and	
		Flexibility Matrices	297
	9.6	Basic Theory of Matrix Force Method	297
	9.7	Method of Computing Matrix X	304
	9.8	Procedure for the Calculation of Internal Forces, Defor-	
		mations, and Flexibility Matrix Using Matrix Force	
		Method	306
*	9.9	Displacement Method of Calculating the Stiffness	
		Matrix	313
	9.10	Partitioning of the Stiffness Matrix	318
		Analogy between the Force Method and the Displace-	
	i i	ment Method	32

INDEX 329