

Contents

Preface	xii
Contributors	xv
1 Introduction	1
<i>B. Jähne</i>	
1.1 Components of a vision system	1
1.2 Imaging systems	2
1.3 Signal processing for computer vision	3
1.4 Pattern recognition for computer vision	4
1.5 Performance evaluation of algorithms	5
1.6 Classes of tasks	6
1.7 References	8
I Sensors and Imaging	
2 Radiation and Illumination	11
<i>H. Haußecker</i>	
2.1 Introduction	12
2.2 Fundamentals of electromagnetic radiation	13
2.3 Radiometric quantities	17
2.4 Fundamental concepts of photometry	27
2.5 Interaction of radiation with matter	31
2.6 Illumination techniques	46
2.7 References	51
3 Imaging Optics	53
<i>P. Geißler</i>	
3.1 Introduction	54
3.2 Basic concepts of geometric optics	54
3.3 Lenses	56
3.4 Optical properties of glasses	66
3.5 Aberrations	67
3.6 Optical image formation	75
3.7 Wave and Fourier optics	80
3.8 References	84

4 Radiometry of Imaging	85
<i>H. Haußecker</i>	
4.1 Introduction	85
4.2 Observing surfaces	86
4.3 Propagating radiance	88
4.4 Radiance of imaging	91
4.5 Detecting radiance	94
4.6 Concluding summary	108
4.7 References	109
5 Solid-State Image Sensing	111
<i>P. Seitz</i>	
5.1 Introduction	112
5.2 Fundamentals of solid-state photosensing	113
5.3 Photocurrent processing	120
5.4 Transportation of photosignals	127
5.5 Electronic signal detection	130
5.6 Architectures of image sensors	134
5.7 Color vision and color imaging	139
5.8 Practical limitations of semiconductor photosensors	146
5.9 Conclusions	148
5.10 References	149
6 Geometric Calibration of Digital Imaging Systems	153
<i>R. Godding</i>	
6.1 Introduction	153
6.2 Calibration terminology	154
6.3 Parameters influencing geometrical performance	155
6.4 Optical systems model of image formation	157
6.5 Camera models	158
6.6 Calibration and orientation techniques	163
6.7 Photogrammetric applications	170
6.8 Summary	173
6.9 References	173
7 Three-Dimensional Imaging Techniques	177
<i>R. Schwarte, G. Häusler, R. W. Malz</i>	
7.1 Introduction	178
7.2 Characteristics of 3-D sensors	179
7.3 Triangulation	182
7.4 Time-of-flight (TOF) of modulated light	196
7.5 Optical Interferometry (OF)	199
7.6 Conclusion	205
7.7 References	205

II Signal Processing and Pattern Recognition	
8 Representation of Multidimensional Signals	211
<i>B. Jähne</i>	
8.1 Introduction	212
8.2 Continuous signals	212
8.3 Discrete signals	215
8.4 Relation between continuous and discrete signals	224
8.5 Vector spaces and unitary transforms	232
8.6 Continuous Fourier transform (FT)	237
8.7 The discrete Fourier transform (DFT)	246
8.8 Scale of signals	252
8.9 Scale space and diffusion	260
8.10 Multigrid representations	267
8.11 References	271
9 Neighborhood Operators	273
<i>B. Jähne</i>	
9.1 Basics	274
9.2 Linear shift-invariant filters	278
9.3 Recursive filters	285
9.4 Classes of nonlinear filters	292
9.5 Local averaging	296
9.6 Interpolation	311
9.7 Edge detection	325
9.8 Tensor representation of simple neighborhoods	335
9.9 References	344
10 Motion	347
<i>H. Haußecker and H. Spies</i>	
10.1 Introduction	347
10.2 Basics: flow and correspondence	349
10.3 Optical flow-based motion estimation	358
10.4 Quadrature filter techniques	372
10.5 Correlation and matching	379
10.6 Modeling of flow fields	382
10.7 References	392
11 Three-Dimensional Imaging Algorithms	397
<i>P. Geißler, T. Dierig, H. A. Mallot</i>	
11.1 Introduction	397
11.2 Stereopsis	398
11.3 Depth-from-focus	414
11.4 References	435
12 Design of Nonlinear Diffusion Filters	439
<i>J. Weickert</i>	
12.1 Introduction	439
12.2 Filter design	440
12.3 Parameter selection	448
12.4 Extensions	451
12.5 Relations to variational image restoration	452

12.6 Summary	454
12.7 References	454
13 Variational Adaptive Smoothing and Segmentation	459
<i>C. Schnörr</i>	
13.1 Introduction	459
13.2 Processing of two- and three-dimensional images	463
13.3 Processing of vector-valued images	474
13.4 Processing of image sequences	476
13.5 References	480
14 Morphological Operators	483
<i>P. Soille</i>	
14.1 Introduction	483
14.2 Preliminaries	484
14.3 Basic morphological operators	489
14.4 Advanced morphological operators	495
14.5 References	515
15 Probabilistic Modeling in Computer Vision	517
<i>J. Hornegger, D. Paulus, and H. Niemann</i>	
15.1 Introduction	517
15.2 Why probabilistic models?	518
15.3 Object recognition as probabilistic modeling	519
15.4 Model densities	524
15.5 Practical issues	536
15.6 Summary, conclusions, and discussion	538
15.7 References	539
16 Fuzzy Image Processing	541
<i>H. Haußecker and H. R. Tizhoosh</i>	
16.1 Introduction	541
16.2 Fuzzy image understanding	548
16.3 Fuzzy image processing systems	553
16.4 Theoretical components of fuzzy image processing	556
16.5 Selected application examples	564
16.6 Conclusions	570
16.7 References	571
17 Neural Net Computing for Image Processing	577
<i>A. Meyer-Bäse</i>	
17.1 Introduction	577
17.2 Multilayer perceptron (MLP)	579
17.3 Self-organizing neural networks	585
17.4 Radial-basis neural networks (RBNN)	590
17.5 Transformation radial-basis networks (TRBNN)	593
17.6 Hopfield neural networks	596
17.7 Application examples of neural networks	601
17.8 Concluding remarks	604
17.9 References	605

III Application Gallery

A Application Gallery	609
A1 Object Recognition with Intelligent Cameras	610
<i>T. Wagner, and P. Plankensteiner</i>	
A2 3-D Image Metrology of Wing Roots	612
<i>H. Beyer</i>	
A3 Quality Control in a Shipyard	614
<i>H.-G. Maas</i>	
A4 Topographical Maps of Microstructures	616
<i>Torsten Scheuermann, Georg Wiora and Matthias Graf</i>	
A5 Fast 3-D Full Body Scanning for Humans and Other Objects .	618
<i>N. Stein and B. Minge</i>	
A6 Reverse Engineering Using Optical Range Sensors	620
<i>S. Karbacher and G. Häusler</i>	
A7 3-D Surface Reconstruction from Image Sequences	622
<i>R. Koch, M. Pollefeys and L. Von Gool</i>	
A8 Motion Tracking	624
<i>R. Frischholz</i>	
A9 Tracking "Fuzzy" Storms in Doppler Radar Images	626
<i>J.L. Barron, R.E. Mercer, D. Cheng, and P. Joe</i>	
A10 3-D Model-Driven Person Detection	628
<i>Ch. Ridder, O. Munkelt and D. Hansel</i>	
A11 Knowledge-Based Image Retrieval	630
<i>Th. Hermes and O. Herzog</i>	
A12 Monitoring Living Biomass with in situ Microscopy	632
<i>P. Geißler and T. Scholz</i>	
A13 Analyzing Size Spectra of Oceanic Air Bubbles	634
<i>P. Geißler and B. Jähne</i>	
A14 Thermography to Measure Water Relations of Plant Leaves .	636
<i>B. Kümmelen, S. Dauwe, D. Schmundt and U. Schurr</i>	
A15 Small-Scale Air-Sea Interaction with Thermography	638
<i>U. Schimpf, H. Haußecker and B. Jähne</i>	
A16 Optical Leaf Growth Analysis	640
<i>D. Schmundt and U. Schurr</i>	
A17 Analysis of Motility Assay Data	642
<i>D. Uttenweiler and R. H. A. Fink</i>	
A18 Fluorescence Imaging of Air-Water Gas Exchange	644
<i>S. Eichkorn, T. Münsterer, U. Lode and B. Jähne</i>	
A19 Particle-Tracking Velocimetry	646
<i>D. Engelmann, M. Stöhr, C. Garbe, and F. Hering</i>	
A20 Analyzing Particle Movements at Soil Interfaces	648
<i>H. Spies, H. Grönig, and H. Haußecker</i>	
A21 3-D Velocity Fields from Flow Tomography Data	650
<i>H.-G. Maas</i>	
A22 Cloud Classification Analyzing Image Sequences	652
<i>M. Wenig, C. Leue</i>	

A23 NO _x Emissions Retrieved from Satellite Images	654
<i>C. Leue, M. Wenig and U. Platt</i>	
A24 Multicolor Classification of Astronomical Objects	656
<i>C. Wolf, K. Meisenheimer, and H.-J. Roeser</i>	
A25 Model-Based Fluorescence Imaging	658
<i>D. Uttenweiler and R. H. A. Fink</i>	
A26 Analyzing the 3-D Genome Topology	660
<i>H. Bornfleth, P. Edelmann, and C. Cremer</i>	
A27 References	662
Index	667